

# FRIS/TI-FRIS

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## Hub Meeting

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### 生き物らしい運動知能の設計原理を求めて

### Exploring Design Principles for Life-like Locomotor Intelligence

#### Summary

Locomotion is the most fundamental intelligence of animals, supporting various behaviors essential for survival. For example, animals can escape from predators and search for food by moving across complex environments. Such situation-dependent locomotor abilities are realized through adaptive motor control via dynamic interactions between the nervous system, body, and environment. Extracting the design principles underlying locomotor intelligence in animals could contribute not only to biological understanding but also to the creation of autonomous robots with high survivability. In this presentation, I will introduce my research using centipedes as a model animal and an interdisciplinary approach combining biology, mathematics, and engineering.

\*Language: English

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参加登録